

ELSETA

IOMOD 8AI

User manual

Elseta 08/09/2021 V1.3

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DECLARATION OF CONFORMITY

(in accordance with ISO / IEC Guide 22 and EN Section 45014) Manufacturer: UAB Elseta Address of the manufacturer L. Zamenhofo str. 3 LT Vilnius, Lithuania

We claim that: The device IOMod 8AI

Conforms to the following standards: EMC: Radiation EN 55022 (Class A) 1 emitted radiation (30-1000MHz) Second radiation conductors (0.15-30 MHz) EN 50082-1 immunity test 1 IEC 801-3: Radio-frequency electromagnetic field 2 IEC 801-2: Electrostatic discharge. 3 IEC 801-4: Quick periodic electrostatic discharges

Additional information:

"The device complies with the Low Voltage Directive 73/23/EEC and EMC Directive 89/336/EEC. Device assembly complies with the RoHS Directive.

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SAFETY REQUIREMENTS

These equipment operating notes must be met for your personal safety as well as to avoid damage to the equipment. These notes are marked with a warning triangle symbol and the various degrees of risk of falling within signs. All work related to electronic systems design, installation, commissioning, adjustment and maintenance should be carried out in accordance with the safety requirements.

SYMBOLS USED BY USER MANUAL



Danger - important notice, which may affect the safety of the user or device.



Attention - notice on possible problems that may arise in individual cases.



Information Notice - the information that is useful advice or special places.



Warning of the danger. The work may only be performed by a qualified professional. Equipment installation, commissioning and maintenance may only be performed by a qualified professional authorized to perform commissioning, grounding and labeling devices, systems and circuits. The person must be aware of occupational safety in the workplace, need to understand the equipment components and electrical equipment, have the knowledge and skills to identify a component beneath the voltage.



To maintain the equipment it is necessary to always turn off the power supply before doing installing or dismantling works. It must be kept in mind that even standalone equipment can have a common ground connection. Power supply, cables and interconnect components must always be inspected before connecting.



This product cannot be implemented or resold to install in areas that are marked as high-security such as nuclear power plants, aircraft navigation, military equipment, transport traffic in management. In such areas, equipment failure can result in of nature damage and human injury.



Do not operate the equipment under extreme weather conditions as they may affect the operation of the equipment.

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1. Introduction

IOMod 8AI is a compact-sized stand-alone Modbus (RTU) or IEC-60870-5-103 analog input controller. IOMod can be used for industrial applications where digital signaling is used and robust communication is needed. IOMod is an ideal solution for applications such as data acquisition, observation, process monitoring, testing and measurement at remote places. It is controlled over Modbus or IEC 60870-5-103 protocol, and can be used with any SCADA system.

2. Features

- 8 analog inputs, each configurable separately
- All inputs are capable of measuring electrical voltage or current
- Inputs can be recalibrated according to the needs of a user
- RS485 communication
- LED input indications, + Data transmission (Rx and Tx) indication.
- Configurable over USB
- Drag-and-Drop firmware upgrade over USB
- A small sized case with removable front panel
- DIN rail mount
- Operating temperature: from -30 to +70°C
- Power Requirements: 12-24 VDC

3. Operational information

IOMod 8AI uses Modbus (RTU) or IEC 60870-5-103 protocol over RS485 interface. A protocol used by a device can be changed by uploading corresponding firmware. Default communication settings: 9600 baud/s baud rate, 8N1 port configuration, Slave address - 1.

a. Common configuration information

- 1. <u>Measurement type.</u> A user can select measurement type (electrical current or voltage) on each channel individually.
- <u>Sensitivity selection</u>. To increase a resolution of input measurement capture, a user can define in which range measurement will occur. The best resolution will be achieved within a shortest selected range. For all possible configurations refer to **Technical Information** and **Configuration over USB** described later in this document.
- 3. <u>Measurement limits</u> can be selected, which in turn set thresholds on underflow or overflow error statuses. Also, if a scaled integer data type is selected, these limits will be converted to values using limits stated in **Casting data range** for Modbus protocol.
- 4. <u>Data type selection</u>. A device can output float or scaled integer data types for each input individually for Modbus. Modbus input register read will then show raw float value (in milliamperes or millivolts) or scaled integer types. When a float data type is selected, each input will be represented as two Modbus registers (32-bits). These values can be later converted to

IEEE-754 standard-compatible float values.

 <u>Casting data range</u>. A device is capable of converting measurements into desired decimal values in a linear manner. For Modbus, a user can select between floating point data type – which will return a raw measurement of either voltage or current and scaled integer type – which conversion is freely definable. Note that the specification for IEC-60870-5-103 only lets 13-bit signed measurands, therefore only cast representation of true value can be used with absolute limits being [-4095, 4095].

Fig. 3.2 shows how raw measurement (current in this case) is converted to an integer type. Conversion is done by defining measurement limits (from -25mA to 25mA) and casting data range (from 0 to 100). Measurement limits define thresholds for overflow and underflow errors respectively; casting data range defines limits (from 0 to 100) that value should be between after recalculation. Such a recalculation can be used in applications that require measurements in relative units such as percentage.

A device can round measurements to lower conversion limit (in this case – to zero) if a measurement is near it: $\pm 15\%$ of measurement value (Fig. 3.2). Live zero correction is a useful option for eliminating noise. As signals always have some noise level, such an option can compensate it to get a true zero value.



Fig. 3.2. Conversion graph from raw measurement to cast integer

b. MODBUS operational information

Each input can be configured to represent 16-bit signed integer value or 32-bit float value. When the float data type is selected, the value will be shown as two registers for one input. When the 16-bit integer data type is selected, a value will be shown as one register. This means addresses of individual input and the maximum number of readable registers can differ according to user configuration.

Configure device over USB terminal. Modbus commands that can be used are shown in the table below.

Supported MODBUS functions

02 (0x02) Read Input Status

Used to read analog input overflow and underflow statuses. First 8 inputs show each input underflow statuses (according to **measurement limits** option) and second 8 inputs show overflow statuses.

04 (0x04) Read Input Registers

Used to read measurements of at most 8 analog inputs. IOMod 8AI has 8 analog inputs from address 0 to address 15 (0000Fh). Different analog inputs can be cast in different data types configured over a USB interface.

Function	Register	Name	Description	Values range
02	00000- 0000F	Read Input Status	Returns overflow and underflow statuses of each input. First 8 shows underflow status, last 8 shows overflow	0 – OK, 1 - error
04	00000- 0000F	Read Input Registers	Returns Input values	0-65535 (decimal) of one Register

Modbus register table

c. IEC 60870-5-103 operational information

IOMod with IEC-60870-5-103 firmware uses a standard communication scheme. Initiation, control messages and queries are initiated by a master (controlling station), while IOMod device (controlled station) only answers requests and sends values. The first message sent by master should be RESET CU to restart communication. When *acknowledge* (ACK) packet is sent from a slave device, a master may proceed with acquiring *General Interrogation* and sending *Time synchronization* packets.

When this initialization is complete, master should poll IOMod device with Class 1 and Class 2 requests. Class 2 is used when master polls for cyclic data. The controlled device responds when spontaneous data exists and master then sends a request for Class 1. Controlled station responds with a time-tagged message.

As IOMod 8AI doesn't have any digital inputs, only analog ones, general interrogation returns nothing. Values of measurements are returned cyclically without any additional request therefore commands sent will be ignored.

4. Technical information

	System	
1.	Dimensions	101 x 119 x 17.5 mm
2.	Case	ABS, black
3.	Working environment	Indoor
4.	Working temperature	-30 +70°C
5.	Recommended operating conditions	5 – 60°C and 20 – 80%RH;
6.	Configuration	USB
7.	Firmware upgrade	USB – mass storage device

	Electrical specifications	
8.	Inputs	 16-bit resolution; Channel-Independent Programmable Input Ranges: Voltage input: Bipolar: ±10.24 V, ±5.12 V, and ±2.56 V Unipolar: 10.24 V, 5.12 V; Current input: Bipolar: ±51.2 mA, ±25.6 mA, and ±12.8 mA Unipolar: 51.2 mA, 25.6 mA; Overvoltage protection up to ±20V;
	Power	
9.	Power Supply	9V to 33V
10.	Current consumption	40mA @ 12VDC, 20mA @ 24VDC

5. Mounting and installation guide

a. IOMod 8AI RS485 interface

IOMod 8AI has integrated 120Ω termination resistor which can be enabled or disabled over USB configuration. It is recommended to use termination at each end of the RS485 cable. See typical connection diagram in Fig. 5.1.





IOMod 8AI has 1/8 Unit load receiver which allows having up to 255 units on a single line (compared to standard 32 units). To reduce reflections keep the stubs (cable distance from main RS485 bus line) as short as possible.

Bipolar inputs

b. IOMod 8AI inputs

Unipolar inputs

A typical application of IOMod 8AI unipolar and bipolar voltage inputs is shown in Fig. 5.2. See **Configuration over USB** chapter for instructions for analog input configuration.

+5V +5V 0V 0V C -5V to +5V 0V to +5V 🔘 -O 0V -5V 0V +10V +10V 0V 0V 🔾 -10V to +10V 0V to +10V O--0 ov 0V -10V (B) ¥ ┢ OMod 8A Ð RS 485 +12/24 VD www.elseta.com +12/24VDC 0 Ċ to RS485 BUS

Fig. 5.2. Voltage input connection diagram for IOMod device

All analog inputs can be configured as current inputs to connect 0-20 mA, 4-20 mA or other current output sensors. Typical application of IOMod 8AI unipolar and bipolar current inputs is shown in Fig.

Bipolar current inputs

5.3. See **Configuration over USB** chapter for instructions for analog input configuration.

Unipolar current inputs



Fig. 5.3. Current input connection diagram for IOMod device

6. Configuration over USB

a. Driver installation

The device requires USB drivers to work as a Virtual COM port. The first-time connection between device and computer could result in "Device driver software was not successfully installed" error (as in Fig. 6.1).



Fig. 6.1. Unsuccessful device software installation error

A user then should manually install drivers by selecting a downloaded driver folder:

- Go to Control Panel -> Device Manager;
- Select a failing device;
- Press "Update driver software"; screen as in Fig. 6.2. should appear:

🕞 🔋 Update Driver Software - Unknown Device	
How do you want to search for driver software?	
Search automatically for updated driver software Windows will search your computer and the Internet for the latest driver software for your device, unless you've disabled this feature in your device installation settings.	
Browse my computer for driver software Locate and install driver software manually.	

Fig. 6.2. Device driver software update message

• Select "x86" driver for a 32-bit machine or x64 for a 64-bit machine. If not sure, select a root folder (folder in which x64 and x86 lay inside, as in Fig. 6.3).

library 🔹 Share with 👻 Burn	New folder			
Name	Date modified	Туре	Size	
퉬 хб4	11/24/2015 15:20	File folder		
鷆 x86	11/24/2015 15:20	File folder		
Ipc-vcom	12/5/2014 20:46	Security Catalog	7 KB	
🗊 lpc-vcom	11/21/2014 23:20	Setup Information	3 KB	

Fig. 6.3. Device driver folder content

b. IOMod configuration via PuTTY terminal

A configuration of IOMod device is done through CLI (Command Line Interface) on the virtual COM port. Drivers needed for Microsoft Windows to install VCOM will be provided. To open up CLI simply connect to specific V-COM port with terminal software (advised to use PuTTY terminal software. If other software is being used, a user might need to send <return> symbol after each command). When connected user should immediately see the main screen. For Modbus check Fig. 6.4, IEC-60870-5-103 - Fig. 6.5.

	IOMOD Configure Terminal (Modbus)
[1] [2] [3] [7] [8] [9] [0]	Slave Address (1) Communication settings Individual channel configuration Set Default Settings Firmware Upgrade Diagnostics Exit

Fig. 6.4. The main menu for IOMod 8AI, Modbus firmware version

	IOMOD Configure Terminal (IEC-103)
[1] [2] [4] [5] [7] [8] [9] [0]	Link Address (1) Baudrate & bits(9600, 8+1) N Parity Data addressing config RS485 Terminating Resistor (Enabled) Individual channel configuration Set Default Settings Firmware Upgrade Diagnostics screen Exit

Fig. 6.5. The main menu for IOMod 8AI, IEC-60870-5-103 version

Navigation is performed by sending digits or other symbols to a terminal. A user then proceeds by following on-screen instructions. For example, to set baud rate, press [2] to enter Communication settings screen; press [1] to edit; enter new configuration; press [RETURN] to save, or [ESC] to cancel changes. When done, press [0] (exit) before disconnecting device. Default values are set by pressing [7] on the main screen, and confirming changes [1].



It is highly advised to exit the main screen before disconnecting device

If the terminal window is closed accidentally, a user can connect the terminal program again, and press any key on a keyboard to show the main menu again.

Modbus Main menu

	Name	Function	Values	Default Values	
[1]	Slave Address	Setting Modbus Slave address	1-247	1	
[2]	Communication settings	[1] Baud rate, [2] Data, Stop and Parity Bits, [3] RS485 Terminating resistor	[1] 100 - 256000, [2] 8 Data bits + 1/2 Stop bits, Even/None/Odd Parity [3] Enabled/Disabled	[1] 9600, [2] 8N1, [3] Enabled	
[3]	Individual channel configuration	Channel configuration Configuration")	Channel configuration screen (see Table "Individual Channel Configuration")		
[7]	Set Default Settings	Sets Default Settings	(1 to confirm, 0 to cancel)	-	
[8]	Firmware Upgrade	Mass Storage Device Firmware Upgrade	(1 to confirm, 0 to cancel)	-	
[9]	Diagnostics	Raw input values	-	-	
[0]	Exit	Exit and disconnect	-	-	

IEC-60870-5-103 Main Menu

	Menu Name	Function	Values	Default Values
[1]	Link Address	Changing link address	1-247	1
[2]	Baud rate, Parity and Stop bits	[1] Set 8 Data bits + 1 Stop bit	[3] 100-256000	[3] 9600 [4] None

		 [2] Set 8 Data bits + 2 Stop bit [3] Configure baud rate [4] Configure Parity 	[4] None/ Odd / Even / Mark/ Space	
[3]	Data addressing config	Enters configuring screen for Input address (function type)	1 – 255	160
[4]	RS485 Terminating Resistor	RS485 120 Ohm Terminating Resistor	[1] Enable [2] Disable	Enabled
[5]	Individual channel configuration	Channel configuration screen (see Table "Individual Channel Configuration")		
[7]	Set Default Settings	Sets Default Settings	(1 to confirm, 0 to cancel)	-
[8]	Firmware Upgrade	Mass Storage Device Firmware Upgrade	(1 to confirm, 0 to cancel)	-
[9]	Diagnostics	Raw input values	-	-
[0]	Exit	Exit and disconnect	-	-

Configuring an individual channel is a job requiring the most effort, therefore an additional table is provided to make a configuration task much easier. Note that number written in brackets shows a number for selection in an IEC-60870-5-103 version.

Individual Channel Configuration Menu

	Menu Name	Function	Values	Default Values
[1]	Measure Current/Voltag e	Selecting this option toggles measurement selection	-	-
[2]	Change sensitivity	Selecting a measurement range	[1] [-10.24 V, 10.24 V], [2] [-5.12 V, 5.12 V], [3] [-2.56 V, 2.56 V], [4] [0 V, 10.24 V], [5] [0 V, 5.12 V]	[1] [-10.24 V, 10.24 V]
[3]	Measurement limits	Entering floating point values to use them for marking overflow/underflow statuses	Floating values in a range defined by measuring sensitivity	-5 mV; 5mV

[4] ²	Cast to a scaled integer/float	Selecting this option toggles value casting selection	-	-				
[5] ^{1 2}	Casting data range	Check 3a. Common configuration information						
[6] ¹ (4)	Live zero tolerance							
0.	Back	Back to last menu screen	-	-				

¹ Only available if casting to a scaled integer is selected

² Not available in IEC-60870-5-103 firmware version

c. Measurements' calibration

Every device is shipped containing factory-predefined calibration coefficients. However, changing temperature and humidity conditions can affect the accuracy of measurements. To get the best accuracy, use the device at room temperature and if that is not possible, calibrate coefficients accordingly.

To enter the calibration screen (Fig. 6.6) from main menu press '@' symbol.

Select a measurement	t to	calibrate:	
[1] Current			
[2] Voltage			
[] Back			

Fig. 6.6. Analog inputs' calibration screen

In the calibration screen, either current or voltage coefficients can be selected. Selecting current by pressing [1] should enter additional screen (Fig. 6.7). Calibrating voltage is an identical process therefore only current setting is explained.



Fig. 6.7. Current calibration screen

[1-8] Change current calibration coeffs for AIn
[*] Change all calibration coeffs at once
[] Cancel current calibration
Select mode for AI1
[1] Manual
[2] Automatic
[] Back
Currently coeff K for AI1 is: 1.0000
Enter new parameter value (<return> to save, <ESC> to cancel):
Currently coeff B for AI1 is: 0.0000
Enter new parameter value (<return> to save, <ESC> to cancel):
Fig. 6.8. Manual calibration coefficients' setting
[1-8] Change current calibration coeffs for AIn



Fig.6.9. Automatic calibration coefficients' setting

All configuration coefficients can either be configured all at once or individually. The coefficient setting for all channels is done manually only. Tweaking individual channels, however, can be automatic (Fig. 6.9) as well as manual (Fig. 6.8). Selecting automatic calibration polls values that user inputs and tweaks coefficients to minimize the additive error. It is therefore advised to scan several values differing by the same value interval to get the best results. Pressing ESC finishes calibration and saves coefficients to non-volatile memory.

d. Protocol simulation over USB

After entering the diagnostics screen, protocol simulator can be turned on by pressing [9]. When it is on, the device will communicate over USB port rather than a RS-485 line. Communication on a RS-485 line is closed and all Modbus or IEC-60870-5-103 commands will only be accepted from USB. To exit this mode device must be restarted.

e. Firmware upgrade over USB

To update device firmware user must:

- Enter the main configuration menu;
- Enter Firmware update screen by pressing [8];
- Confirm update by pressing [1];

The device should now enter Firmware Upgrade mode.



It is recommended to close the terminal window after entering firmware upgrade mode

The device should then reconnect as a mass storage device (Fig. 6.10).



Fig. 6.10. Mass storage device notification

Delete existing file "firmware.bin" and simply upload new firmware file by dragging and dropping as in Fig. 6.11.

						, 🗖	x
	puter 🕨 CRP1 ENABL	D (E:)		✓ ⁴ → Search	CRP1 ENABLD (E:)		Q
Organize 🔻 Share	with 🔻 🛛 Burn	New folder			:== •		0
J Music	 Name 	Date modified	Туре	Size			
Videos	irmware 📄	2/6/2009 10:10	BIN File	128 KB			
Computer Local Disk (C:) CRP1 ENABLD (E Network	H						
1 item							

Fig. 6.11. Mass storage device for firmware upload

Reconnect device and check the firmware version. It should have changed.



The settings data structure may differ from version to version, therefore it is highly advised to choose **Default Settings** after writing new firmware. Otherwise, there is no guarantee that all device features are going to work properly.

7. Testing With "THE VINCI" software

To test IOMod with default settings, a device should be connected through RS485 to Modbus master. Example using "The Vinci Expert" device as serial interface converter and adapter to PC with "The Vinci" software. Default settings for Modbus – 9600 baud/s baud rate; 8 data, no parity, 1 stop bit. When opening "The Vinci" software, choose Modbus serial – Master mode. In the Settings tab, choose station number (default – 1); configure tags (as described in section **Modbus operational information**); Press Start and go to "Statistic" tab as shown in Fig. 7.1.

O TH	E VINCI	PROTOCOL	ANALYZ	ER		-		1				•	_	
File	Tags	Options	Help											
		Protocol: Mode:	MODBL Master	JS serial	v v		Stop		Port A:	COM6 -	Baudrate:	9600	 Format: even,8, 	1 - Set VI
	Settings	С	Console		Events	Sta	atistic	The Vinci Expe	ert			Tags	Format	
Stat	ion		Functi	on			Addres	s Value	Count	Name]	Tag0-		
1			Read	Holding	Registers	(04)	0	17674	134	AnalogI	_	Name	: AnalogInputs	-
1			Read	Holding	Registers	(04)	1	-3444	134	-	_	Value	17674	
1			Read	Holding	Registers	(04)	2	17674	134	-	_			
1			Read	Holding	Registers	(04)	3	-884	134	-	_	Tag1-		
1			Read	Holding	Registers	(04)	4	17674	133	-	_	Name	: AnalogInputs	-
1			Read	Holding	Registers	(04)	5	-2164	133	-	_	Value	: 17674	
1			Read	Holding	Registers	(04)	6	17674	133	-	_			
1			Read	Holding	Registers	(04)	7	-6004	133	-	_	lag2		
1			Read	Holding	Registers	(04)	8	17674	133	-	_	Name		*
1			Read	Holding	Registers	(04)	9	-7284	133	-	-	Value	E	
1			Read	Holding	Registers	(04)	10	17674	133	-	_	rTag3-		
1			Read	Holding	Registers	(04)	11	-6004	133	-	-	Name		
1			Read	Holding	Registers	(04)	12	17674	133	-	_	- Home		
1			Read	Holding	Registers	(04)	13	-6004	133	-	_	Value	0	
1			Read	Holding	Registers	(04)	14	17674	133	-	_			
1			Read	Holding	Registers	(04)	15	-2164	133	-	_	****	Format: Float Value: 2212,315 Update tags Shov	v value

Fig. 7.1. Testing IOMod Modbus communication using "THE VINCI" software

Prot	ocol: IEC 60870-5-1 Mode: Master	03	v	Stop	Port A:	COM19 - Baud	rate: 9600	Ÿ	Format :	none,8,1 - Se	Set VINCI ports Device manager Swap por
Settings	Console	Events		Statistic	The Vinci Expert						System Tags
	Couse	ASDU	FUN	INF	Value	Status	TimeTag	Count	Name]	Address
I=005)	Start/restart		255	1 (0)		ASC=IOMOD8AI F		0			Custom ASDU ASDU:
I=003)	cyclic	1	255	160 (0)	04095(099.9756%)	OV=1 IV=0	-	46	-		Couse:
I=003)	cyclic	1	255	160 (1)	04095(099.9756%)	OV=1 IV=0	-	45	-		
I=003)	cyclic	1	255	160 (2)	04095(099.9756%)	OV=1 IV=0	-	45	÷		General interogation
I=003)	cyclic	1	255	160 (3)	04095(099.9756%)	OV=1 IV=0	-	45	-		Send SCAN number:
I=003)	cyclic	1	255	160 (4)	04095(099.9756%)	OV=1 IV=0	-	45	-	_	Clock synchronisation-
I=003)	cyclic	1	255	160 (5)	04095(099.9756%)	OV=1 IV=0	-	45	-	-	Send DIV SM [
I=003)	cyclic	1	255	160 (6)	04095(099.9756%)	OV=1 IV=0	-	45	-		
I=003)	cyclic	1	255	160 (7)	04095(099.9756%)	OV=1 IV=0	-	45	-	_	PC time 2018/12/14 08:53:58
										-	General command
											FUN: 255 INF: 0 RII:

Fig. 7.2. Testing IEC-60870-5-103 communication using "THE VINCI" software

Default settings for IEC-60870-5-103 - 9600 baud/s baud rate; 8 data, no parity, 1 stop bit. After

opening "The Vinci" software choose IEC-60870-5-103 serial – Master mode. In "Settings" tab, choose station number (default – 1) and ASDU (default - 1); press "Start" and go to "Statistic" tab as shown in Fig. 7.2.

8. Information of the equipment manufacturer



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Work hours: I-V 8:00-17:00

9. Document history

Version	Date	Author	Description
V1.0	2017.04.03	L.S.	First version
V1.1	2017.05.30	J.S.	Technical information, Mounting and installation guide
V1.2	2018.12.17	A.J.	 Added more explanation on how to configure the device and its inputs. Added calibration information Marked differences between versions better Updated images Improved language
V1.3	2021.08.09	R.S.	Chenged manufacturer information